Factor analysis of tongue shapes

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(Received 12 October 1976; revised 12 May 1977)

A new analytic procedure PARAFAC has been applied to the description of the shape of the tongue in English vowels. The procedure models the data in terms of a unique set of posibly explanatory factors. It solves in parallel for factors in several data sets, simultaneously describing the differences among data sets in terms of different relative involvement of these common factors. Tracings were made of x-rays taken during the pronunciation of 10 English vowels by five speakers. The positions of the tongue in these 50 vowels were quantized in terms of 13 superimposed grid lines. PARAFAC analysis shows that the data can be described in terms of two factors. One factor generates a forward movement of the root of the tongue accompanied by an upward movement of the front of the tongue. The second factor generates an upward and backward movement of the tongue. Movements from front to back involve decreasing amounts of factor one. Movements from high to low vowels involve decreasing amounts of factor two. Different speakers use the two factors to different degrees which may be associated with their individual anatomy. The correlation between the observed data and that predicted by the model is greater than 0.96.

PACS numbers: 43.70.Bk, 43.70.Gr

INTRODUCTION

A. The nature of the problem

During speech, the surface of the tongue assumes hundreds of subtly different shapes. Each of these shapes is a particular nonuniform curve, usually one having no simple representation in terms of words or equations. Nonetheless it becomes clear by simply examining the curves, that they are related to one another in some kind of orderly way. For example, there appear to be systematic patterns of relationships among the tongue shapes used by a given speaker for producing different vowels, as well as patterns relating the shapes used by different speakers to produce the same vowel. Such patterns of tongue shape variation are of great interest to speech scientists, but, for methodological reasons, attempts to measure and accurately describe these patterns have run into serious difficulties. The basic problem has been one of finding a way to represent the curved surface of the tongue so that the interesting relationships among different tongue shapes can be easily identified and measured. This is the problem to which this article is primarily addressed.

1. Pictorial representations

One of the simplest yet most complete methods of representing a tongue shape is to use a picture of that shape. Such pictures, particularly tracings from x-ray photographs, form an essential starting point for the investigation of tongue-shape variations. But while the information in pictorial representations is relatively complete, it is not sufficiently compact: tracings do not separate the essential information from the nonessential. For this reason, comparison of two or more tongue shapes by means of pictures does not provide a precise analysis of the relationship among the several shapes, i.e., it does not reveal the rule relating the shapes to one another. What is needed is a compact, hopefully quantitative, representation that still can capture the subtle differences among closely related shapes of the tongue.

2. Analysis into features

One potentially effective way of studying the relationships among different tongue shapes would be to reduce each tongue shape to a description in terms of a few common underlying features. Descriptions of this kind would also be useful for studying relationships between tongue shapes and other variables such as formant frequencies, and for studying linguistic questions, such as historical patterns of language change. Once a set of common features for all the tongue shapes has been defined, and each particular shape has been described in terms of its values on these common features, it then becomes possible to compare any two or more shapes by simply comparing their respective feature values.

The next question thus becomes "By what method of analysis can one find the most appropriate set of features for describing tongue shapes and their relationships to one another?" The availability of a good analysis method, appropriate to the data at hand, can make a big difference in the success or failure of the search for an optimal feature set. A case in point is the search for features to describe the acoustic properties of vowels, a search which has been much more successful than the one for features to describe articulatory properties of vowels. Much of the progress with acoustic features was made possible by the use of spectral-analysis techniques. Spectral analysis reduced the complex sounds of different vowels into a common set of underlying spectral components and allowed vowels to be compared in terms of their respective values on these common components. This led, in turn, to the identification of a small number of features—the formant frequencies—which appear to capture most of the information relevant to acoustic relations among vowels.

Since at least in part the ear analyzes sounds into spectral components, this may help account for the success of spectral analysis in the description of acoustic properties. However, there is no similar a priori reason to lead us to expect that articulatory properties would be well suited for spectral analysis (but see Ref.
Another two-number method of characterizing shapes of the tongue has been suggested by Lindblom and Sundberg. Their technique is to use one number to specify the degree of distortion of the tongue shape from a neutral shape, and another to specify the position of the point of maximum displacement.

Finally, Liljenkrantz has shown how a curve representing the shape of the tongue can be described in terms of its Fourier components. Using a partly polar and partly Cartesian coordinate system which enabled him to straighten out the vocal tract, he showed that the profile of the tongue could be fairly well described in terms of the magnitude and phase of a fundamental frequency. He shows quite conclusively that the tongue shapes in vowels can be described in terms of two or three numbers.

Other experimenters have constructed more elaborate models of the tongue, which will not be reviewed here. These researchers are all more concerned with modeling the physiological forces moving the tongue. They are not trying to find a minimal set of descriptively adequate features.

C. Comparison of the current and previous approaches

There are certain limitations in the previous attempts to specify features for tongue shape. There is, first of all, an arbitrariness to the system employed. It is the intuition of the researcher that determines whether geometric figures, narrowest points, or specified distortions will be used to describe the shape of the tongue. Secondly, with the exception of the spectral-analysis model, there is no explicit measurement of the fit of the model to the data. Thirdly, (again with the exception of the spectral-analysis model), there is no explicit optimization of the fit of the model under variation of parameters within the model. No mathematical guarantee is present that the features chosen insure optimal fit, subject to particular explicit constraints. Fourthly, patterns of individual differences among speakers are not integrated into the model. Finally some of the models (e.g., the narrowest-point models and the spectral-analysis model) do not lend themselves to interpretation as possible descriptions of psychologically real feature systems.

The factor-analytic approach to be adopted in this study is not subject to these particular limitations. It presents an integrated mathematical model which simultaneously describes (a) the features of tongue shape for English vowels; (b) the relationships among English vowels in terms of these features; and (c) person differences in vowel production (for our five speakers) in terms of these features. A very general specification system is adopted which is transformed into a more specific set of feature shapes by optimization of fit of the model to the data, rather than by intuitive selection of shapes by the researcher. In this sense, the procedure for developing the model might be considered more objective or less arbitrary, i.e., more theoretically neutral and strictly determined by the characteristics of the data, than previously used procedures.

In this study, feature discovery starts with sets of
x-rays of vocal-tract shapes for five people. The x-rays are traced and the tracings of the tongue are characterized in numerical terms by means of an algorithm that is as objective as possible. (We are well aware, however, that experimenter judgment of what is relevant is often involved both in tracing x-rays and in measuring the tracings.) Then certain minimal assumptions are made about the characteristics of possible features of tongue shape. The model assumes that at least our five speakers (and presumably all speakers of English) use some of a small number of these features, that these features add together to produce the observed vocal tract shapes, and that the elementary features can be described in terms of patterns of displacement of the tongue from a reference position of the vocal tract. Given the data base and assumptions just described, an algorithm proceeds to select from the set of possible features the best specific features for vocal tract shapes, along with feature values for vowels and speakers, by using a three-way factor analysis or three-way principal-component analysis procedure as described below. The best vocal-tract features and vowel/person feature values are the ones that do the best job of reproducing the actual x-ray measurements across all vowels and speakers. The fit of the feature-model predictions to the observed data is optimized by making the sum of the squared errors of these reproductions as small as possible.

The intuition or educated judgment of the researchers still enters in, of course. It enters, for example, when the obtained solutions of the model must be interpreted, and in deciding whether some artifacts of measurement or other errors have distorted the solution. Furthermore, the model simply determines the best solution for each given number of factors. The researcher has to decide whether or not the solution is satisfactory, or whether more or fewer factors are required. Nonetheless, the features are determined in a relatively standardized and clearly specifiable fashion. The restricted points at which the researcher’s judgment operates can be described, as can the evidence supporting each particular choice, and the choices are generally explicit enough to enable them to be independently evaluated by other interested persons who have access only to the reports on the research.

I. METHOD

A. Construction of the data base

The data that were analyzed have been described elsewhere. Briefly, from a larger body of data, we selected high-quality audio recordings and cine-filmograms of five speakers saying sentences of the form “Say (vowel) again.” The vowels included /i, i, e, æ, ø, u/ as in “heed, hid, hayed, head, had, hod, hawed, hoed, hood, who’d.” These vowels cover the range of articulatory movement that occur in English vowels. The vowel /æ/ as in “bird” was not included, because it is known that this vowel can be produced in more than one way.

A single frame in the film was chosen for each of the

![FIG. 1. The reference lines used for characterizing the positions of the tongue for one of the speakers. The vowel is /æ/ as in “had.” For reasons given in the text the solid lines were used, rather than the dashed lines that are more nearly perpendicular to the middle of the vocal tract.](image-url)

10 different vowels as said by each of the five speakers. In the case of the vowels /i, e, æ, a, o/ the most steady-state part of the second formant was selected. Whenever possible this procedure was also followed for the other vowels. But for some speakers at least one of these vowels was diphthongal throughout. In these cases a point approximately 30 msec after the first consonant was chosen. In each case, the corresponding frame in the film was located and traced.

1. Reference grids

The vocal-tract shapes were characterized in terms of a set of reference lines of the kind shown in Fig. 1. Because head shapes differ, a different reference grid had to be used for each speaker. The procedure used to generate the reference grid for each speaker was as follows: First we estimated the position of the midline of the vocal tract when in position for the vowel /æ/ as in “had.” We then measured the length of this line from the estimated position of the glottis to a point midway between the two lips. This length was divided into 18 sections, subject to the following conditions: (a) the middle of section 3 should be below the level of the epiglottis; (b) the middle of section 4 should be above the root of the epiglottis; (c) sections 1–3 should be the same length; (d) sections 4–18 should be the same length; (e) the lengths of sections 1–3 should be as similar to the lengths of sections 4–18 as the constraints allow. If possible within these constraints (as it was for three of our five speakers), all the sections were made the same length. For the other two speakers the first three sections were slightly longer. It was thought preferable to anchor the measurements around the epiglottis in this way, since this is the only fixed landmark on the tongue. It was hoped that this procedure would increase within- and cross-speaker comparability. An additional consideration was the fact that data on the sections below

the root of the epiglottis are less reliable because of problems in seeing the position of the tongue on x-rays in this region. We did not want to have four unreliable measurements in the case of some subjects and three for others.

When the midline of the vocal tract had been determined and divided into 18 sections as described above, reference lines were drawn through the center of each section. These lines were as nearly as possible perpendicular to the midline of the vocal tract, subject to two additional constraints: (i) in the pharyngeal region, they were all parallel to each other, with the majority of them being as perpendicular to the back wall of the pharynx as possible; and (g) when the slope of the reference lines changed so as to remain perpendicular to the curving midline, the changes of slope were always as uniform as possible. Thus, for the speaker represented in Fig. 1, the solid lines were used instead of the dotted lines.

In the case of the reference lines that crossed the hard palate, the alveolar ridge, and the teeth (sections 13–17 on Fig. 1) which are fixed structures on the upper surface of the vocal tract, an arbitrary end point was marked on each line at a fixed distance (45 mm on the x-ray tracings) from the upper surface of the vocal tract. End points were then marked on each of the other lines so that the set of end points followed a smooth curve within the body of the tongue (as shown by the series of solid points at the ends of the reference lines in Fig. 1). The precise shape of this curve is irrelevant since we will be considering only deviations of the tongue from its average position for each subject. This will subtract out any constant effects introduced by choice of the shape of this curve. (See Sec. I B.)

2. Measurements

Once a grid had been established for a given speaker, all his tongue shapes were characterized by measuring the distance along the reference lines between the surface of the tongue and each of these 17 points. The distance between the lips was also measured. All the original measurements were in millimeters to the nearest 0.5 mm. They were subsequently converted to centimeter life size by dividing by 16.

The data set was verified by means of a computer program which simplified the comparison of the measurements with the original x-ray tracings. Each measurement, except for the distance between the lips (point 18), was subtracted from the constant representing the distance from the upper surface of the tract to the arbitrary end point. The resulting subtracted values would be equivalent to cross sections (sagittal dimensions) of the vocal tract if the tongue were moving in a vocal tract with a smooth, fixed upper surface. (In practice, of course, there is considerable movement of the velum and of the back wall of the pharynx, which we are not concerned with in this study of tongue movements.) Using the pseudosagittal dimensions, the computer program diagrammed the vowels of different subjects with reference to a common base line representing the upper surface of an arbitrary vocal tract. An example is given in Fig. 2, which shows a superimposition of the measurements for each speaker saying the vowel [o] as in “hoed.”

Our analysis of the data using these techniques showed that there is a great deal of apparently random variation, particularly in the lower part of the pharynx (points 1–3). This may be due to individual anatomical variation, but, as we have already mentioned, our x-ray tracings may not be very reliable in this area. Comparison of the diagrams with the original x-ray tracings also showed that point 17 (just inside the lips) was often beyond the tip of the tongue, and simply indicative of the position of the teeth. The measurement for point 18 (the distance between the lips) is also obviously not relevant to characterizations of tongue shape. Accordingly we selected for analysis the data corresponding to points 4–16.

The pseudosagittal dimensions (i.e., the original measurements with the constants subtracted) for each of the 13 points, 10 vowels, and 5 speakers are shown in Table I. The measurements are presented in this way for the convenience of other research workers who wish to diagram the positions of the tongue. But it should be remembered that, since the upper surface is in constant motion, Table I does not give the true sagittal dimensions of the vocal tract.

B. Factor analysis models and procedures

1. The conceptual model

The original pseudosagittal measurements may be turned into measurements of tongue displacements, by defining an arbitrary reference position for each speaker, and considering each observed x-ray shape as a displacement of the tongue surface from that speaker’s reference position. Analyzing these displacements, we seek to uncover a few underlying displacement patterns that combine in various amounts to produce particular observed shapes. These displacement patterns or gestures of the tongue act together to carry the tongue from
its reference position to a given observed position. Each gesture corresponds to a single factor that will be uncovered by the analysis procedure. In the models to be considered here, the basic set of gestures is the same for all vowels, and for all speakers, but differences between vowels and speakers are described in terms of differences in the relative amounts of the various gestures employed. The common set of basic tongue gestures is the set of articulatory features discovered by the analysis. The amount of each gesture used to generate the observed displacements for a particular vowel are the feature values of that vowel. In the PARAFAC three-way analysis, different speakers are also distinguished by systematically different emphasis on each of the various basic tongue gestures.

Let $x_{ij}$ represent the measurement along the $i$th grid line ($i$th-tongue coordinate line) of the $j$th vowel, as measured for the $i$th speaker (e.g., in Table 1, $x_{111} = 2.45$, $x_{18105} = 1.65$, and $x_{511} = 2.40$). We next define the reference measurement for the $i$th grid line of speaker $k$ as follows:

$$r_{ijk} = \frac{1}{10} \sum_{j=1}^{10} x_{ij}.$$  

\(1\)
The displacement of the tongue corresponding to any observed x-ray shape is computed by simply taking the difference between the measurements for that shape and the reference-position measurements, as follows:

$$d_{ij} = (x_{ij} - r_{ij}).$$  \hspace{1cm} (2)

Table I contains 5 sets of 10 vectors, each vector with 13 components. The problem of decomposing the deviation versions of these 50 vectors into different combinations of a few common underlying vectors is a classical problem for principal-component and factor analysis. While the general properties of these methods are well known, it will be useful to clarify their relation to the particular conceptual model described above. This will also facilitate discussion of a newer and less well known three-way generalization of these methods (see Refs. 1 and 2) that will be used as the primary analytic technique of this article.

2. The two-way mathematical model

The classical two-way factor analytic techniques can not handle triply subscripted (three-way) data arrays. Therefore we will initially consider only one of the five speakers (perhaps an average speaker). A given data point for this speaker can be represented by $x_{ij}$, and a displacement score by $d_{ij}$. The classical factor and principal-component models would represent the underlying component of this displacement for $w$ factors as follows:

$$d_{ij} = t_{i1}v_{j1} + t_{i2}v_{j2} + \ldots + t_{iw}v_{jw} + e_{ij}.$$  \hspace{1cm} (3)

In this equation the $t$ and $v$ values are weights (classically called loadings and scores, respectively) which describe the relation between each underlying gesture and the surface variables of the data set. The $t_{i1}$ and $t_{i2}$ coefficients, for example, describe the relative effect of factors 1 and 2 on displacements along tongue grid line $i$. The $v_{j1}$ and $v_{j2}$ values, on the other hand, describe the relative contributions of factor (gesture) 1 and 2 to the $j$th vowel. The $e_{ij}$ term is an error term that represents the difference between the actual measured displacement $d_{ij}$ and the value predicted by the sum of the contributions of the factors. The discrepancy may be thought of as due to errors of measurement, or to specific variance for that tongue section $i$ not shared by any other tongue section, or some combination of these. Technically, principal-component analysis and factor analysis make different assumptions about the statistical properties of the $e_{ij}$ values (e.g., whether they are uncorrelated), but for the purposes of the present discussion we will ignore these distinctions. We will concentrate on the principal-component case where the $e$ values are the least-square residuals of prediction of the displacement values from the factor loadings and scores (the $t$ and $v$ coefficients). Also, for simplicity, we will use the term “factor” to refer either to factors or principal components.

As an example, consider a basic tongue gesture which involves a large displacement of the tongue surface along grid line $i$, so that the $t_i$ coefficient will be large. Further, assume that this gesture is a major component of the observed surface displacement for vowel $j$, so that the $v_{ij}$ coefficient is also large. The value of $d_{ij}$ predicted by the model is the sum of the effects of each of the factors (gestures), i.e., the first $w$ terms on the right-hand side of Eq. (3). So, in the example we are considering, the product of the $t$ and $v$ coefficients for this component of the surface displacement would be large, and contribute substantially toward the sum of the underlying components which estimates the final observed displacement, $d_{ij}$. On the other hand, if either the effect of the gesture along tongue grid line $i$ were small, or the amount of that gesture involved in the production of vowel $j$ were small, the contribution of that component to this particular $d_{ij}$ would be small. The error term $e_{ij}$ is not used to predict tongue displacements, but rather to reconcile such predictions with the actual observed displacements. It expresses the fact that a component for the $j$th tongue section peculiar to the $j$th vowel will have to be added.

A traditional factor analysis of a single set of tongue-shape deviation measurements produces two tables. One table is a set of values describing the tongue gestures or articulatory features of tongue shape. This is the table of $t$ values, and for a solution in which two factors are extracted (i.e., $w = 2$), it would have two columns (one for each basic gesture), and as many rows as there were tongue grid lines entered into the analysis (in this case 13). The entries in this table describe, for each gesture or articulatory feature, the relative size of tongue displacement occurring along each of the grid lines. Thus, a column of this table describes the shape of a given displacement gesture. The second table, the table of $v$ values, gives the amount that each gesture contributes to the observed displacement for each vowel. The entries in this table can be interpreted as the values of the extracted features for each vowel.

The solution obtained by a two-way factor analysis has a number of desirable characteristics: it gives a description of underlying tongue gestures—our articulatory features—and also provides a description of vowel relationships in terms of these features. However, it suffers from at least two shortcomings: (a) it does not provide a way of incorporating individual speaker differences into the model; (b) it does not provide a unique solution. The first shortcoming is evident from the two-way nature of the required data, but the second shortcoming requires some further explanation.

As a simple example, consider the equation $x + y = 20$. This equation has no unique solution, since an infinite number of $x$, $y$ pairs will satisfy the weak constraints imposed by the specified relationship. Similarly, the values of the factor loadings in the two-way factor model are not sufficiently constrained by the model to uniquely determine the description of the underlying factors. Given one set of $t$ and $v$ values which provide an optimum fit to a particular set of data, we can always find other sets of $t$ and $v$ values (call one such set $t'$ and $v'$, for example) which provide exactly the same fit of the model to the data. For example, if we defined our new factor loadings as $t'_{ij} = t_{ij} + t_{2i}$, $v'_{ij} = v_{ij} - t_{ij}$, we would obtain a new version of factor 1 which would incorporate
those aspects common to old factors 1 and 2, and a new
version of factor 2 which would incorporate those as-
pects which differentiated old factors 1 and 2. Given the
7 values, it is a straightforward matter to determine the
new 8 values and 7 values so that 8 8 8 8 8 does just as
good a job of reproducing the data as the old t and v val-
ues.

Selecting the preferred solution in the face of this non-
uniqueness is the classical “rotation” problem of two-
way factor analysis (called “rotation” because a change
of coordinates, such as the one described above, can be
considered a rotation of axes in the factor space). Psy-
cologists and others who have used two-way factor
analysis have devised special procedures for rotation
of factors into preferred form. Foremost among these is
the well known principle of “simple structure,” which
(loosely speaking) selects the particular solution in which
as many as possible of the t values are near zero.
(Kaiser’s Varimax roughly approximates this objective).
While this simplifies the mathematical description of
any factor, there is no reason, with our tongue data, to
presume that this procedure will lead to patterns of fac-
tor loadings which are empirically more basic or “real”
(e.g., which might correspond to the empirical sources
of variation which underlie these data—see Refs. 1 and
2 for further discussion of “explanatory” validity).

Because of these shortcomings of two-way factor anal-
ysis and principal-component analysis, a three-way
analytic procedure called PARAFAC was adopted as the
primary method of analyzing this tongue data. Not only
does this procedure allow explicit incorporation of sub-
ject differences, but, if the data are adequate, it can pro-
vide a unique solution for the underlying factors.

3. The three-way (PARAFAC) mathematical model

The model discussed so far has considered variations
in only two modes—tongue points and vowels. The third
mode of our data set—variations in tongue shape across
speakers—is explicitly represented in the three-way
principal-component and factor-analytic model of our
data. Here the deviation of the original three-way data
set is represented as follows:

$$d_{ijk} = t_{ij}v_{jk}s_{ki} + t_{ij}v_{jk}s_{km} + \cdots + t_{iw}v_{jk}s_{kw} + e_{ijk}.$$  \hspace{1cm} (4)

This model is the same as the traditional model, ex-
cept that each term is multiplied by an additional co-
efficient. The first of these coefficients, the s, value,
represents the relative emphasis of the first feature by
person k. Similarly s gives the relative degree of use
of feature w by person k. The PARAFAC analysis will
provide, in addition to the tables of t and v values de-
scribed previously, a third table of s values describing
the relative degree to which each speaker emphasizes a
given feature across all vowels.

The incorporation of this third mode has an important
property besides facilitating analysis of three-way data.
It provides one possible solution to the problem of non-
uniqueness present in two-way factor analysis. We can
best see how this occurs by referring again to our ex-
ample of the simple equation \(x + y = 20\). One solution to
the nonuniqueness of x and y for such equations consists
of providing additional constraints on the solution by
bringing in additional information about the unknown
variables. In terms of our original analogy, unique val-
ues of x and y can be determined if we consider several
related equations in parallel, such as \(x + y = 20\) and \(2x
+ 3y = 55\). If we require the same values of x and y to
satisfy both equations, a unique solution is obtained.
Similarly, PARAFAC obtains a unique solution for the
set of factor loadings by considering several sets of
equations in parallel (in our case, one set of equations
for each subject).

But not all additional equations will do. Note that the
coefficients of x and y must not have the same ratio to
one another in the two simultaneous equations, if the
second equation is to provide additional constraints and
therefore guarantee a unique solution. The equation \(2x + 2y
= 40\), for example, would not add any new constraints.
So, too, with PARAFAC: the ratio or relative empha-
sis of the two (or more) factors must differ across at
least some of the subjects in order to provide the addi-
tional constraints necessary to obtain unique factors.
(For further discussion and mathematical proofs, see
Refs. 1 and 2). This point will become important in our
discussion of the obtained tongue factors, below.

The PARAFAC model will provide a solution which is
meaningful or explanatory only to the extent that the data
conform to the mathematical model described above.
This model assumes that there is a particular kind of
systematic difference among speakers. It presumes that
each speaker can be characterized by coefficients in-
dicating his degree of use of each feature. Thus if
speaker A uses more of factor 1 than does speaker B
for a particular vowel, then speaker A must use more
of factor 1 than speaker B in all other vowels. The ratio
of any two speakers’ usage of a given factor must be the
same for all vowels. If this assumption of systematic
variation is valid, then a unique and explanatory set of
features (factors) can be obtained from the data. (See
Ref. 1, pp. 19–22 for further discussion of types of
three-mode data variation in relation to the PARAFAC
model).

4. Analysis procedure

a. Criterion for convergence. Each PARAFAC solu-
tion is computed by starting with a random set of values
for the factor loadings (i.e., random t, v, and s tables)
and incrementally improving on this first guess by
means of an iterative process. This process changes
these values in small steps improving the fit of the solu-
tion to the data at each step until a final optimal solu-
tion is reached. The stepwise changes in factor load-
ings are large at first, and become smaller as the solu-
tion approaches its final form at which point no more
stepwise improvement is possible for that solution.
Convergence of this iterative process onto a stable set
of values is determined by comparing each value of t
and v with their values earlier in the iterative process
(in this study we used the values 30 iterations previous-
ly). Convergence is considered adequate when the
largest change in any value is less than 0.001. This
criteria corresponds to a cumulative change over 30
iterations of less than 0.1% in the mean observed val-
ues. Experience has shown that when changes in the values become this small over that many iterations no number of further iterations is going to appreciably alter the solution.

b. Testing uniqueness of solutions. Before settling on a final solution for a given data set it is necessary to determine whether there are any alternative solutions that might be found if different random starting values are used in the iterative procedure. With error-free appropriate data, PARAFAC will provide a unique solution whenever the necessary independent systematic variation in factors across speakers, vowels and tongue points has occurred and whenever the number of factors being extracted matches the number underlying the data. With noisy data, however, both pseudo-non-uniqueness and pseudo-uniqueness can occur. Therefore it is necessary to investigate the uniqueness properties of the data in question at each dimensionality of interest.

To do this an analysis is performed with three different random starting positions for each dimensionality being investigated. These three converged solutions are then compared to one another to determine whether all three solutions represent the same factors. If all solutions agree, the common solution is tentatively assumed to be unique for that dimensionality. If all three do not agree, the several versions are compared to determine their relation to one another and to solutions at lower and higher dimensionality.

Non-uniqueness may be due to a true multiplicity of possible solutions, which may be the result of extracting too many factors, or of insufficient independent variation of the effects of the factors across speakers, vowels, or tongue points. It may also be due to presence of a local optimum. If one of the competing solutions has a substantially worse fit to the data, it is not considered to be evidence of a true multiple solution at that dimensionality, but rather as the result of a local optimum which has trapped the iterative procedure before it had reached the true optimum. Alternative solutions of approximately equal fit value (where \( r^2 \) differs by less than 0.005) indicate the true multiplicity of underlying solutions, and are suggestive of the extraction of too many factors. Because of noise in the data, however, attempts to extract too many factors will often fail to produce non-uniqueness. On the other hand, non-uniqueness can occasionally occur when two few factors have been extracted. For example, one may have a stable, unique, four-dimensional solution but two competing solutions at three dimensions. On closer examination it may become evident that factors one, two, and four of the four-dimensional solution appear in one of the three-dimensional solutions, and factors one, two, and three appear in the other. This example demonstrates how comparison of the content of alternative competing solutions with each other and with solutions at different dimensionalities is sometimes necessary to adequately interpret the nature of the observed non-uniqueness.

c. Examining solutions across the range of possible dimensionalities. In order to determine the number of dimensions that will be used to describe the data, three solutions are computed at each dimensionality from one dimension up to at least three dimensions above the maximum number of dimensions probably present in the data. In this study, since it was anticipated that only a few factors would be involved, solutions were computed for up to seven dimensions. It was expected that the higher-dimensional solutions (beyond four) would not contribute useful new information. The analysis of these higher dimensionalities was performed mainly to confirm that the fit value of the solution does not substantially improve for these dimensionalities. A plot of fit versus dimensionality is then constructed (see, e.g., Fig. 12) and examined to determine if there is a sharp bend or elbow in the curve indicating the highest dimensionality where substantial improvement in fit is obtained by allowing for additional dimensions.

In addition to this plot of fit versus dimensionality of solutions (which is often quite ambiguous in that it does not have a clear elbow) the actual form of the solution at different dimensionalities is compared, and the nature of the changes from one dimensionality to the next is used as a guide to help determine the appropriate dimensionality. Interpretability of individual solutions and of the changes from one solution to another are used to help guide choice of dimensionality.

The best means of testing the "genuineness" (statistical stability) of additional factors was unfortunately not feasible for the data analyzed here. This technique relies on the comparison of two solutions, each of which is based on one-half of the total subject sample randomly divided. Spurious factors or those too weak to be well determined by the data will not cross validate in these split-half solutions.

d. Additional analysis at likely dimensionalities. Once a likely dimensionality is selected on the basis of the criteria described above, three additional solutions are run at this dimensionality as well as at the dimensionality just below and just above this dimensionality. If the preferred dimensionality is \( n \), this provides six different random starting positions for the \( n \)-dimensional, the \( n-1 \)-dimensional and the \( n+1 \)-dimensional solutions. With six solutions a statistical claim about uniqueness can then be made. If all six random starting positions give the same final version of the solution, the probability is less than 0.05 that another equally likely solution exists at that dimensionality. If alternative solutions exist this process gives a better idea of whether there are two or more than two possibilities.

The preferred solution, based on all the criteria mentioned above, is then selected for study and interpretation in more detail.

II. RESULTS

As we have noted, the first task in considering the results of a PARAFAC analysis is to decide how many factors underlie the variations in the data. For expository reasons this point will be considered after we have discussed the nature of the factors that are present. To begin with we will assume that there are only two identifiable factors in our data. We can then show how these factors can be used to describe the variations in the data in each of the three modes of the analysis. We will first discuss how the movements of individual points
TABLE II. Factor loadings $t_{11}$ and $t_{12}$ for each point on the tongue, and the contribution of each point to the mean-squared error in reproducing the data, for the two-dimensional PARAFAC solution.

<table>
<thead>
<tr>
<th>Point</th>
<th>Factor 1</th>
<th>Factor 2</th>
<th>Contribution to error of fit</th>
</tr>
</thead>
<tbody>
<tr>
<td>(i)</td>
<td>$(t_{11} - 0.05049)$</td>
<td>$(t_{12})$</td>
<td>0.00249</td>
</tr>
<tr>
<td>(5)</td>
<td>-0.8817</td>
<td>1.0940</td>
<td>0.00235</td>
</tr>
<tr>
<td>(6)</td>
<td>-1.0500</td>
<td>0.9461</td>
<td>0.00215</td>
</tr>
<tr>
<td>(7)</td>
<td>-1.1640</td>
<td>0.5893</td>
<td>0.00274</td>
</tr>
<tr>
<td>(8)</td>
<td>-1.1370</td>
<td>0.0056</td>
<td>0.00222</td>
</tr>
<tr>
<td>(9)</td>
<td>-0.9540</td>
<td>0.4504</td>
<td>0.00222</td>
</tr>
<tr>
<td>(10)</td>
<td>-0.5536</td>
<td>0.9281</td>
<td>0.00205</td>
</tr>
<tr>
<td>(11)</td>
<td>0.1349</td>
<td>1.2440</td>
<td>0.00194</td>
</tr>
<tr>
<td>(12)</td>
<td>0.8719</td>
<td>1.4180</td>
<td>0.00207</td>
</tr>
<tr>
<td>(13)</td>
<td>1.2590</td>
<td>1.3670</td>
<td>0.00202</td>
</tr>
<tr>
<td>(14)</td>
<td>1.4060</td>
<td>1.2420</td>
<td>0.00150</td>
</tr>
<tr>
<td>(15)</td>
<td>1.3190</td>
<td>0.9281</td>
<td>0.00236</td>
</tr>
<tr>
<td>(16)</td>
<td>0.9063</td>
<td>0.4905</td>
<td>0.00444</td>
</tr>
</tbody>
</table>

Total mean-squared error = 0.03055

Fig. 4. The proportions of $t_{11}$ and $t_{12}$ required for the vowel /i/ as in "heed." The solid lines represent the tongue shape for the vowel. The dashed line indicates an arbitrary reference position. Lines standing out from the dashed line indicate deviations associated with $t_{11}$ and $t_{12}$. The deviations associated with $t_{11}$ are to the left or below those associated with $t_{12}$.

A. Tongue points

The PARAFAC procedure shows that the shape of the tongue can be described in terms of the values shown in Table II, which are the values for the tongue-point coefficients $t_{11}$ and $t_{12}$ in Eq. (4). These two sets of coefficients are represented graphically in Fig. 3. Each may be thought of as determining a possible movement of the tongue. Each movement consists of a deviation of the tongue from its reference position (shown by solid points) either in the direction of the arrow or away from it. The possible size of the movement for each point is indicated by the length of the arrow through that point. For example, consider a vowel in which the first factor has a large negative value, and the second factor has a zero value. In this vowel the tongue shape will be as shown by the solid line in the left-hand diagram.

Each of the English vowels can be considered to be a combination of certain proportions of these two sets of constants. Figure 4 shows the proportions of these two sets of constants that are required to produce the vowel /i/ as in "heed." In this vowel the proportion of factor 1, $t_{11}$, is fairly large, and the proportion of the second factor, $t_{12}$, is somewhat smaller. The contribution of each factor is shown as a set of lines deviating from the mean tongue position. The contributions of $t_{12}$ are to the left or below those of $t_{11}$. The line representing the vowel is the sum of the two deviations. The position of the lips is estimated from other data, and the position of the point immediately behind the lips is the mean of the position of the lips and the point on the tongue nearest to the lips. The positions of the first three points just above the glottis are extrapolated from the points determined by the PARAFAC solution.

Figure 5 shows in a similar way the combinations of proportions of $t_{11}$ and $t_{12}$ that occur in /a/ as in "hod." This vowel is mainly associated with large negative proportions of $t_{12}$. Figure 6 shows the combinations of proportions of $t_{11}$ and $t_{12}$ that occur in /u/ as in "who’d." In this case both factors are involved, often resulting in opposite deviations. In order to produce the upward and backward movement of the tongue, a positive value of $t_{12}$ is required; but in order to keep the front of the tongue down a negative value of $t_{11}$ must occur.

There is a point below the soft palate that is virtually unaffected by the first factor. Similarly, there is a point in the upper part of the pharynx that is very little affected by variations in the second factor. The first factor is associated with comparatively large movements of points in the front of the mouth, whereas the second factor is associated with larger movements in the back.
of the mouth. In general it appears that \( t_{14} \) determines a forward movement of the root of the tongue together with a raising of the front of the tongue. This movement is very similar to the action of the genioglossus muscle. On the other hand \( t_{12} \) determines an upward and backward movement of the tongue. Loosely speaking this factor can be thought of as corresponding to the pull of the styloglossus muscles. We hasten to add, however, that we do not think it entirely appropriate to associate either factor with particular muscles or muscle groups. The factors are simply sets of constants that enable us to characterize tongue shapes in terms of two variables, one representing the proportion of \( t_{14} \) that is present in a given vowel, and the other representing the proportion of \( t_{12} \).

The PARAFAC solution has some similarities to the characterization of tongue positions proposed by Lindblom and Sundberg (Ref. 8). They characterize tongue positions in terms of a two-dimensional space in which the vowels \([i, a, u]\) are each considered to be maximal distortions of the neutral tract, with \([i]\) having this distortion in the palatal region, \([u]\) in the velar region, and \([a]\) in the pharyngeal region. Other vowels are then said to be intermediate in the place of maximum distortion, and in the degree of this distortion. Their notion is that vowels can be specified in terms of a mechanism for making a lump (and a corresponding hollow) in the neutral shape of the tongue, the two parameters being the position and size of the lump. The PARAFAC solution shows that tongue shapes can indeed be characterized in terms of distortions from a reference shape. But in this solution the tongue position is the sum of two distortions, one having minimum and maximum values for \([o]\) and \([i]\), and the other having minimum and maximum values for \([a]\) and \([u]\).

We should also note that there is a good fit between the original data and the reconstruction of the data using a PARAFAC model. The correlation between these two is very high \((r = 0.9626)\). The mean-squared error is 0.0305 cm. Table II shows the proportion of this error that is contributed by each point on the tongue. It may be seen that with the exception of point 16, which is near the tip of the tongue, each point contributes a similar proportion of the error. The greater error associated with the tip of the tongue may be due to the fact that its exact position has very little effect on the quality of most vowels. However, it must also be remembered that this point is often difficult to locate reliably on x-rays. The shadow of the tongue in this region is often obscured by the teeth.

### Table III

<table>
<thead>
<tr>
<th>Vowel</th>
<th>Factor 1 ((v_{j1}))</th>
<th>Factor 2 ((v_{j2}))</th>
<th>Contribution to error of fit</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>1.5220</td>
<td>0.6931</td>
<td>0.00341</td>
</tr>
<tr>
<td>2</td>
<td>0.9730</td>
<td>0.3293</td>
<td>0.00237</td>
</tr>
<tr>
<td>3</td>
<td>1.0430</td>
<td>0.4190</td>
<td>0.00292</td>
</tr>
<tr>
<td>4</td>
<td>0.7739</td>
<td>-0.1704</td>
<td>0.00225</td>
</tr>
<tr>
<td>5</td>
<td>0.3366</td>
<td>-0.5361</td>
<td>0.00485</td>
</tr>
<tr>
<td>6</td>
<td>-0.3107</td>
<td>-2.0370</td>
<td>0.00400</td>
</tr>
<tr>
<td>7</td>
<td>-1.0720</td>
<td>-1.2360</td>
<td>0.00322</td>
</tr>
<tr>
<td>8</td>
<td>-1.3780</td>
<td>0.2591</td>
<td>0.00195</td>
</tr>
<tr>
<td>9</td>
<td>-1.0490</td>
<td>0.5826</td>
<td>0.00271</td>
</tr>
<tr>
<td>10</td>
<td>-0.8333</td>
<td>1.6870</td>
<td>0.00274</td>
</tr>
</tbody>
</table>

B. Vowel contrasts

Table III shows the values \( v_{j1} \) and \( v_{j2} \) that are required for reconstructing each vowel. These values are represented graphically in Fig. 7. It may be seen that vowel 1, the vowel \(/i/\) as in "heed," requires a maximum value of \( v_{j1} \) and a near maximum value of \( v_{j2} \). Vowels 2–5, which are the other front vowels \(/i, e, e, æ/\) as in "hid, hayed, head, had," also require positive values of \( v_{j1} \), and decreasing values of \( v_{j2} \). Vowels 6 and 7, the low back vowels \(/o, ə/\) as in "hoed, hood, who'd," have positive values of factor 2, but negative values of factor 1.
FIG. 7. The values of $v_H$ and $v_R$ for the 10 vowels in Table III.

There is a strong similarity between the arrangement of the vowels in Fig. 7, and their arrangement in more traditional vowel charts. In fact $v_H$ and $v_R$ determine a somewhat distorted formant space. Variations in the first factor are positively correlated with the second formant, and the second factor is inversely proportional to the first formant. In comparing Fig. 7 with a traditional formant chart it must also be remembered that formant frequencies are considerably affected by the lip opening, which will be continually increasing for the vowels /a/-/a/ on the left of the figure.

Another way of considering the values shown in Table III is in terms of the reconstructed tongue shapes for the mean speaker. These shapes are shown in Fig. 8. They may be compared with the means of the observed displacements of the tongue for each vowel, which are also shown in Fig. 8. Whenever there is a noticeable difference between the original data and the reconstructed shapes, the curve for the original data is indicated by $o$. It is apparent that the PARAFAC analysis allows us to reconstruct mean tongue shapes that are very much in accord with the original data, and do not differ sub-

stantially in any of the regions that are important from the point of view of the function of the vocal tract.

C. Differences between speakers

The five speakers had different coefficients for the two factors, as shown in Table IV. It should be noted that all these coefficients have negative signs. As may be seen from Eq. (4), estimates of the data are the sums of two triple products. The sign of the products depend on the signs of each of the three coefficients. If two of the signs are arbitrarily determined, then the correct sign for the product must be determined by the sign of the third component—the speaker loadings. The signs for the values for the points on the tongue were arranged so that they could be given a plausible physiological interpretation. Those for the vowels were arranged so that the graph of $v_H$ versus $v_R$ corresponded as much

<table>
<thead>
<tr>
<th>Speaker</th>
<th>Factor 1</th>
<th>Factor 2</th>
<th>Contribution to error of fit</th>
</tr>
</thead>
<tbody>
<tr>
<td>$k$</td>
<td>($s_{k1}$)</td>
<td>($s_{k2}$)</td>
<td></td>
</tr>
<tr>
<td>1</td>
<td>-0.4253</td>
<td>-0.2705</td>
<td>0.00412</td>
</tr>
<tr>
<td>2</td>
<td>-0.6869</td>
<td>-0.3590</td>
<td>0.00591</td>
</tr>
<tr>
<td>3</td>
<td>-0.3708</td>
<td>-0.3682</td>
<td>0.00680</td>
</tr>
<tr>
<td>4</td>
<td>-0.3383</td>
<td>-0.4872</td>
<td>0.00785</td>
</tr>
<tr>
<td>5</td>
<td>-0.4654</td>
<td>-0.3111</td>
<td>0.00584</td>
</tr>
</tbody>
</table>

FIG. 8. Reconstructed tongue positions and mean observed displacements of the tongue for the five speakers for each of the 10 vowels. Whenever there is a noticeable difference between the reconstructed and the original data, the original data is indicated by $o$ alongside the tongue positions.
as possible to a traditional vowel chart. But the measurement convention for tongue position measured downward from the roof of the mouth, and so a "raised" tongue (closer to the roof of the mouth) produced negative tongue deviations. As a result the signs on the speaker values all have to be negative.

As shown in Fig. 9, for four of the five speakers, the higher the value of factor 1, the lower the value of factor 2. Speaker 2 does not follow this pattern in that the weight of factor 1 is usually high while the value of factor 2 is also considerable.

There may be physiological reasons why one factor has a higher weight than another for some speakers. We do not want to give much emphasis to this point, but it seems that, within our limited data, the longer the pharynx in comparison with the oral cavity, the less the influence of factor 2. The correlation between the absolute value of $s_{2a}$ and the ratio between the pharynx-cavity length (from grid line 1 to grid line 9), and the oral-cavity length (grid lines 9-16) is $-0.903$ ($p < 0.05$). This particular relationship, which is shown in Fig. 10, is largely determined by one speaker. On the other hand, a higher absolute value of factor 1 is correlated with a longer oral cavity. The length of the pharynx or of the tract as a whole has less effect on the use of fac-

![Figure 9](image1)

**FIG. 9.** The relations between the two factors for each of the five speakers.

![Figure 10](image2)

**FIG. 10.** The relation between factor 2, $s_{2a}$, and the ratio of pharynx-cavity to oral-cavity length.

![Figure 11](image3)

**FIG. 11.** The relation between factor 1, $s_{1a}$, and the oral-cavity length.

![Figure 12](image4)

**FIG. 12.** The relation between the mean-squared error and the number of factors in the analysis. For comparison, $r^2$ values were $1D=0.793$, $2D=0.927$, $3D=0.942$, $4D=0.956$, $5D=0.966$, $6D=0.975$, $7D=0.982$.

For our five speakers the correlation between the absolute values of $s_{2a}$ and the length of the oral cavity (grid lines 9-16) was $0.900$ ($p < 0.05$). But as may be seen from Fig. 11, which displays this relation graphically, this result should be regarded with caution, since it depends on one speaker.

**D. Number of factors**

The PARAFAC analysis procedure finds the best analysis of the data for a given number of factors. From our results we can tell how much error there is in attempting to describe the data in terms of any number of factors from one to seven. Figure 12, shows the mean-squared error for each of these conditions, together with the variance of the data, which is taken to be equivalent to the mean-squared error when no factors have been extracted. It may be seen that a single factor ac-
### TABLE V. A comparison of one-, two-, and three-dimensional solutions.

<table>
<thead>
<tr>
<th></th>
<th>One factor</th>
<th>Two factors</th>
<th>Three factor (a)</th>
<th>Three factor (b)</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>1</td>
<td>2</td>
<td>1</td>
<td>2</td>
</tr>
<tr>
<td><strong>Tongue points</strong></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>4</td>
<td>-0.873</td>
<td>-0.595</td>
<td>-1.190</td>
<td>-0.584</td>
</tr>
<tr>
<td>5</td>
<td>-1.038</td>
<td>-0.881</td>
<td>-1.094</td>
<td>-0.875</td>
</tr>
<tr>
<td>6</td>
<td>-1.095</td>
<td>-1.050</td>
<td>-0.946</td>
<td>-1.054</td>
</tr>
<tr>
<td>7</td>
<td>-1.032</td>
<td>-1.164</td>
<td>-0.589</td>
<td>-1.178</td>
</tr>
<tr>
<td>8</td>
<td>-0.788</td>
<td>-1.157</td>
<td>-0.006</td>
<td>-1.162</td>
</tr>
<tr>
<td>9</td>
<td>-0.489</td>
<td>-0.954</td>
<td>-0.459</td>
<td>-0.987</td>
</tr>
<tr>
<td>10</td>
<td>-0.039</td>
<td>-0.554</td>
<td>-0.928</td>
<td>-0.590</td>
</tr>
<tr>
<td>11</td>
<td>0.565</td>
<td>0.195</td>
<td>1.244</td>
<td>0.102</td>
</tr>
<tr>
<td>12</td>
<td>1.148</td>
<td>0.872</td>
<td>1.418</td>
<td>0.845</td>
</tr>
<tr>
<td>13</td>
<td>1.405</td>
<td>1.259</td>
<td>1.367</td>
<td>1.241</td>
</tr>
<tr>
<td>14</td>
<td>1.460</td>
<td>1.406</td>
<td>1.224</td>
<td>1.392</td>
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<tr>
<td>15</td>
<td>1.283</td>
<td>1.319</td>
<td>0.928</td>
<td>1.308</td>
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<tr>
<td>16</td>
<td>0.804</td>
<td>0.906</td>
<td>0.491</td>
<td>0.900</td>
</tr>
<tr>
<td><strong>Vowels</strong></td>
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<td></td>
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<td></td>
</tr>
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<td>1</td>
<td>1.573</td>
<td>1.522</td>
<td>0.693</td>
<td>1.553</td>
</tr>
<tr>
<td>2</td>
<td>0.945</td>
<td>0.973</td>
<td>0.329</td>
<td>1.032</td>
</tr>
<tr>
<td>3</td>
<td>1.046</td>
<td>1.043</td>
<td>0.419</td>
<td>1.051</td>
</tr>
<tr>
<td>4</td>
<td>0.519</td>
<td>0.774</td>
<td>-0.170</td>
<td>0.748</td>
</tr>
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<td>5</td>
<td>-0.024</td>
<td>0.331</td>
<td>-0.526</td>
<td>0.285</td>
</tr>
<tr>
<td>6</td>
<td>-1.327</td>
<td>-0.311</td>
<td>-2.037</td>
<td>-0.474</td>
</tr>
<tr>
<td>7</td>
<td>-1.501</td>
<td>-1.072</td>
<td>-1.236</td>
<td>-1.067</td>
</tr>
<tr>
<td>8</td>
<td>-0.959</td>
<td>-1.378</td>
<td>-0.259</td>
<td>-1.364</td>
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<tr>
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<td>-1.049</td>
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<td>-1.010</td>
</tr>
<tr>
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<td><strong>Persons</strong></td>
<td></td>
<td></td>
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<td></td>
</tr>
<tr>
<td>1</td>
<td>-0.491</td>
<td>-0.425</td>
<td>-0.271</td>
<td>-0.423</td>
</tr>
<tr>
<td>2</td>
<td>-0.763</td>
<td>-0.696</td>
<td>-0.359</td>
<td>-0.698</td>
</tr>
<tr>
<td>3</td>
<td>-0.487</td>
<td>-0.371</td>
<td>-0.368</td>
<td>-0.374</td>
</tr>
<tr>
<td>4</td>
<td>-0.543</td>
<td>-0.338</td>
<td>-0.487</td>
<td>-0.331</td>
</tr>
<tr>
<td>5</td>
<td>-0.543</td>
<td>-0.465</td>
<td>-0.311</td>
<td>-0.462</td>
</tr>
</tbody>
</table>

Counts for a considerable part of the error. There is a further large decrease in the error if we assume that there are two factors instead of one; but there are not comparable decreases in the error when additional factors are taken into account. Each factor beyond two produces only a small, fairly constant, increase in the goodness of fit. It seems probable that each of these additional factors simply accounts for some of the random effects due to measurement error and other irregularities. The sharp bend in the fit curve at two factors and smoothness of descent thereafter suggest that there are only two identifiable factors underlying the nonrandom variations in the data. The correlation between the original set of measurements and the values generated by the two-factor analysis is 0.9626.

The notion that there are only two factors is substantiated by the data in Table V, which shows the factor loadings on the assumption that there are one, two, and three factors. Two different three-factor solutions are presented, since different random starting positions produced different results. In the first alternative solution the first two factors are much the same as in the two-factor solution, and the third factor has only a small effect since it has very low values for all speakers except for speaker three. In this solution the third factor may be accounting for noise in the data, or for some pattern specific to speaker three. In the other solution the first factor in the two-factor solution has simply split into two very similar factors. Non-uniquenesses of this kind are very good indications that the analysis is trying to extract more factors from the data than can be detected. In addition, this solution did not converge to a stable set of values. All the other solutions in Table V took less than 90 iterations to converge to values which did not vary by more than 0.001 over the last 30 iterations. But the two similar factors in this third solution did not converge to stable values even by 300 iterations. All these indications suggest that the current data set is best described in terms of two factors. This does not necessarily mean that English vowels can always be described in terms of two factors. It is possible that a weak potential third factor is confounded with noise in the somewhat limited data set at hand.

### III. DISCUSSION

#### A. Descriptive adequacy

The PARAFAC analysis described above selects a model which provides a description of the tongue shapes of English vowels for five speakers. The description is
based on a fully explicit (and general) x-ray measurement procedure, and the model is optimally fitted to the data with a high correlation ($r > 0.96$). Tongue shapes are described both compactly and quantitatively in terms of two features, each of which represents the pattern of the tongue displacement from a reference position, at a fixed number of points along its length. Patterns of variation in tongue shape among vowels and among speakers, are also described in a systematic, quantitative manner. Each English vowel is assigned a unique representation in terms of the two features of tongue shape (output by PARAFAC as the vowel coefficients). The relationships among the feature values for different vowels is consistent with the similarity among the vowels' tongue shapes, as judged by a phonetician's intuition, or by casually examining the x-ray tracings. Finally, variations in patterns of tongue shape among different speakers are described quantitatively by the variation in the relative degree to which the two features are associated with them. The value of a given feature for a particular speaker was shown to be correlated with some gross anatomical properties of the speaker's vocal tract.

B. Explanatory value of the features

Given that the features extracted by PARAFAC in the current experiment meet the criteria for descriptive adequacy, one may go on to ask whether these features represent some underlying physiological or linguistic reality, or whether they simply provide for a convenient mathematical description of the data. The answer in part depends on whether the data conform to what Harshman (Refs. 1 and 2) refers to as a system-variation model. In such a model, a single set of underlying factors is viewed as influencing all the objects under consideration. The system influence is such that any aspects of the data-collection situation that alter a given factor's influence on the objects, alters its effects on all of the objects in the same proportion. With reference to the current experiment, the system-variation assumption translates as follows: while there may be some differences among speakers in the degree to which they use the extracted features in producing vowels, for a given pair of speakers, those differences must be in a constant proportion for all vowels. PARAFAC claims that if the condition of system variation is met, then the factors it extracts describe the entities that underlie the patterns of variation in the system. We need to consider, then, whether the assumption of system variation can be shown to be a reasonable approximation to the structure of the data at hand.

There is prima facie evidence for thinking that the hypothesis of system variation could be applicable to the present data set. This evidence lies in the fact that the speaker coefficients in the PARAFAC solution do show a fair amount of variability for both of the two features. Thus, speakers differ in their weightings on the features. This variability was shown to be correlated with anatomical differences between the speakers. This correlation makes it appear unlikely that the differences in speaker coefficients are solely due to the model's accounting for noise in the data. Rather, it seems to indicate that there is some systematic variation among speakers. However, whether or not that pattern of variation is proportional across all vowels is not yet known. Various ways of assessing whether this assumption is met will be discussed in a further paper.

An affirmative answer to the question of system variation implies that the factors extracted by the PARAFAC analysis correspond to some of the real sources of variation underlying the data. Moreover, the system-variation model—if appropriate—has other interesting implications. In particular, it allows us to construct a model characterizing the articulatory vowel space employed by a given dialect, while still accounting for speaker variation within that dialect. It should be recalled that the PARAFAC analysis yields a single representation of the articulatory space of vowels, in terms of their values on the two features of tongue shape. This vowel space can be taken as the single underlying vowel space for the speakers under consideration. Variation between the speakers is limited to stretching or shrinking of the vowel space along its axes. This limit of individual variation to shrinking and stretching along the various factor axes amounts to a fairly strong constraint on how the individuals within a dialect can differ from one another. It rules out the possibility of the vowel space differences between two speakers of the same dialect being specific to individual vowels. Harshman and Pntum have proposed a similar use of PARAFAC analysis for normalizing differences in formant frequencies of sets of vowels spoken by different speakers.

Further important questions remain to be answered before theoretical questions of interpretation should be considered in detail: (a) is the sample large enough for a stable solution; (b) how well will these factors generalize to other sets of English speakers; (c) how well will they generalize to speakers of other languages. Once such questions of reliability and generalizability have been answered, a number of interesting more detailed psychological and linguistic questions can be framed in terms of the dimensions of tongue-shape variation uncovered by this type of analysis.

ACKNOWLEDGMENT

This research was supported in part by a grant from the National Institute of Neurological and Communicative Disorders and Stroke.

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5The same model is developed from the point of view of multidimensional scaling in J. D. Carroll and J. J. Chang, "Analysis of individual differences in multi-dimension scaling via
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